

# Dr. Zhenyu Wu

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## EDUCATION

**Texas A&M University, College Station, Texas, the United States** 08/2017-09/2021  
Doctor of Philosophy in Computer Science, Advised by Prof. *Zhangyang (Atlas) Wang*  
**The Ohio State University, Columbus, Ohio, the United States** 08/2015-05/2017  
Master of Science in Computer Science, Advised by Prof. *Han-Wei Shen*  
**Shanghai Jiao Tong University, Shanghai, China** 09/2011-06/2015  
Bachelor of Engineering in Information Security, Advised by Prof. *Cunqing Hua*

## RESEARCH INTERESTS

1. Building practical perception systems that are: (a) **robust** to perturbations/degradations and distribution shifts[C1,C4,C9]; (b) **efficient** for both inference and training[C5,C6,C13,J1]; (c) **ethical** for individual privacy and group fairness[C7,C12,J3,J4].
2. Solving **low-level** and **high-level** vision problems that include: (a) dehazing[J2] and image enhancement[C10]; (b) object detection[C9] and action detection[C1,C2,C3]; (c) text spotting[C6]; (d) pose estimation[C7]; (e) tracking[C4].

## PUBLICATION

- [C1] Y. Zhai, Z. Liu, **Z. Wu**, Y. Wu, C. Zhou, D. Doermann, J. Yuan, and G. Hua, “SOAR: Scene-debiasing Open-set Action Recognition”, **ICCV**, 2023.
- [C2] K. Kahatapitiya, Z. Ren, H. Li, **Z. Wu**, M. Ryoo, and G. Hua, “Self-supervised Pretraining with Classification Labels for Temporal Activity Detection”, **AAAI**, 2023.
- [C3] **Z. Wu**, Z. Ren, Y. Wu, Z. Wang, and G. Hua, “TxVAD: Improved Video Action Detection by Transformers”, **ACM MM**, 2022.
- [C4] X. Hu, **Z. Wu**, H. Miao, S. Fan, T. Long, Z. Hu, P. Pi, Y. Wu, Z. Ren, Z. Wang, and G. Hua, “E<sup>2</sup>TAD: An Energy-Efficient Tracking-based Action Detector”, Arxiv Preprint, 2022.
- [C5] X. Hu, ..., **Z. Wu**, ... et. al. “The 2020 Low-Power Computer Vision Challenge”, **AICAS**, 2021.
- [C6] Z. Hu, P. Pi, **Z. Wu**, Y. Xue, J. Shen, J. Tan, X. Lian, Z. Wang, and J. Liu, “E<sup>2</sup>VTS: Energy-Efficient Video Text Spotting From Unmanned Aerial Vehicles”, **CVPR UG2+ Workshop**, 2021.
- [C7] **Z. Wu\***, S. Hoang\*, S. Lin, Y. Xie, W. Fan, Y. Lin, and Z. Wang, “3D-Aware Multi-modal Guided Hand Generation for 3D Hand Pose Synthesis”, **ACM MM**, 2020.
- [C8] Y. Zheng, **Z. Wu**, Y. Yuan, T. Chen, and Z. Wang, “PCAL: A Privacy-Preserving Intelligent Credit Risk Modeling Framework based on Adversarial Learning”, Arxiv Preprint, 2020.
- [C9] **Z. Wu**, K. Suresh, P. Narayanan, H. Xu, H. Kwon, and Z. Wang, “Delving into Robust Object Detection from Unmanned Aerial Vehicles: A Deep Nuisance Disentanglement Approach”, **ICCV**, 2019.
- [C10] P. Uplavikar, **Z. Wu**, and Z. Wang, “All-In-One Underwater Image Enhancement using Domain-Adversarial Learning”, **CVPR UG2+ Workshop**, 2019.
- [C11] P. Narayanan, **Z. Wu**, H. Kwon, Z. Wang, and R. Rao, “Overview of Machine Learning-based Perception Algorithms for Unstructured and Degraded Visual Environments”, Artificial Intelligence and Machine Learning for Multi-Domain Operations Applications, 2019.

- [C12] Z. Wu, Z. Wang, Z. Wang, and H. Jin, “Towards Privacy-Preserving Visual Recognition via Adversarial Training: A Pilot Study”, **ECCV**, 2018.
- [C13] J. Wu, Y. Wang, Z. Wu, Z. Wang, A. Veeraraghavan, and Y. Lin, “Deep  $k$ -Means: Re-Training and Parameter Sharing with Harder Cluster Assignments for Compressing Deep Convolutions”, **ICML**, 2018.
- [J1] X. Hu, Z. Jiao, A. Kocher, Z. Wu, J. Liu, J. Davis, G. Thiruvathukal, and Y. Lu “Evolution of Winning Solutions in the 2021 Low-Power Computer Vision Challenge”, **IEEE Computer**, 2023.
- [J2] P. Narayanan, X. Hu\*, Z. Wu\*, M. Thielke, J. Rogers, A. Harrison, J. Agostino, J. Brown, L. Quang, J. Uplinger, H. Kwon, and Z. Wang, “A Multi-purpose Real Haze Benchmark with Quantifiable Haze Levels and Ground Truth”, **IEEE TIP**, 2023.
- [J3] Z. Wu, Z. Wang, Y. Yuan, J. Zhang, Z. Wang, and H. Jin, “Black-Box Diagnosis and Calibration on GAN Intra-Mode Collapse: A Pilot Study”, **ACM TOMM**, 2021.
- [J4] Z. Wu\*, H. Wang\*, Z. Wang, Z. Wang, and H. Jin, “Privacy-Preserving Deep Action Recognition: An Adversarial Learning Framework and A New Dataset”, **IEEE TPAMI**, 2020.

## PROFESSIONAL EXPERIENCE

Researcher @ Wormpex AI Research, Seattle, WA

10/2021-Present

Report to Dr. Zhou Ren, Dr. Yi Wu, and Dr. Gang Hua

### 1. Efficient Multi-Task Integration on Edge Devices

- Model: designed an ultra-efficient multi-task model for one-stage detection and pose estimation
- Data: Built an OpenCV-based annotation tool for multi-objects’ bounding box and pose keypoints with pseudo labels
- Deployment: deployed the multi-task model on edge devices using TensorRT (250 fps) and RKNN-toolkit (40 fps)
- Accuracy: combined heatmap-based and regression-based in one-stage way for better pose estimation
- Accuracy: collected detection and pose estimation related benchmarks for better model pretraining
- Robustness: designed a hard-sample mining strategy to acquire out-of-distribution samples
- Efficiency: proposed a multi-scale branch pruning strategy for acceleration ( $\times 1.25$  faster)
- Efficiency: implemented an ultra-efficient post-processing module in C++ ( $\times 250$  faster over Python)
- Efficiency: proposed a hardware-agnostic quantization workflow that uses both Quantization-Aware Training (QAT on multi-gpu training device) and Post-Training Quantization (PTQ on target edge device) to achieve minimal accuracy loss ( $< 1$  mAP), with de-quantization before PTQ and after QAT

### 2. Product Display Check by Text Segmentation

- Proposed a text segmentation-based “display check” model for products on the shelves
- Encapsulated the “display check” model as an http service in Docker
- Collect datasets from retail business for training and evaluation

### 3. E<sup>2</sup>TAD: An Energy-Efficient Tracking-based Action Detector [C3, J1, ICCV-21 LPCV 1<sup>st</sup> Prize]

- Duty: served as the team leader (8 grad students) and main contributor
- Award: won the **1<sup>st</sup> Place out of 31 Teams** at *ICCV-21 Low-Power Computer Vision Challenge*
- System design: designed a tracking-based spatio-temporal video action detector
- Robustness: presented a view-invariant and occlusion-robust person Re-Identification (ReID) model
- Efficiency: reduced the parameter storage and energy consumption of ReID by  $40\times$  and  $60\times$  respectively, via data-driven adaptive pruning and quantization-aware training with minor accuracy loss
- Efficiency: proposed two lightweight YOLO variants for human detection achieving 10 FPS on Raspberry Pi 3B+
- Efficiency: proposed a cache-friendly computation pipeline that traded memory with less data movement to save energy
- Efficiency: proposed two dynamic inference strategies to save energy consumption

**Research Assistant @ Texas A&M University, College Station, TX**

08/2017-09/2021

Advised by Dr. Zhangyang Wang

**1. Privacy-Preserving Action Recognition via Adversarial Learning [ECCV-18, TPAMI-20]**

- Fulfilled the privacy-preserving purpose by applying learnable active degradation on image/video data in smart home setting
- Formulated a three-party game among the utility, the privacy budget and the degradation module
- Proposed novel training strategies, evaluation protocols, and visualization methods
- Collected a benchmark by annotating privacy-related attributes on existing action recognition dataset

**2. E<sup>2</sup> VTS: Energy-Efficient Video Text Spotting from UAV [C4, C5, CVPR-20 LPCV 2<sup>nd</sup> Prize]**

- Duty: served as the team leader (6 grad students) and main contributor
- Award: won the **2<sup>nd</sup> Place out of 11 Teams** at *CVPR-20 Low-Power Computer Vision Challenge*
- System design: a two-step text spotting pipeline that revisited RCNN's crop & resize training strategy
- System design: EAST model for detection and CRNN model for recognition on low-resolution images
- Efficiency: a multi-stage image processor to select the highest-quality frame in a sliding window manner by rejecting text-free frames, cropping non-text regions, and rejecting out-of-distribution frames
- Efficiency: an LBP and Canny edge-based algorithm to identify the key frames and crop text regions to save energy consumption
- Efficiency: structured pruning and quantization-aware training to reduce both model size and computation cost with minimal accuracy loss
- Efficiency: used L1 filter, ADMM pruner etc. methods in NNI tool to prune both models by about 75% parameters
- Efficiency: used dynamic/QAT quantization methods in PyTorch to quantize both models

**Research Intern @ Wormpex AI Research, Seattle, WA**

05/2020-08/2020

Advised by Dr. Zhou Ren, Dr. Yi Wu and Dr. Gang Hua

**End-to-End Video Action Detection with Transformers [MM-22]**

- Proposed a Transformer-based Paradigm to do action detection in an end-to-end way
- Proposed a Person Localization Transformer (PTx) and an Action Classification Transformer (ATx)
- Proposed a Hardness-Aware Curriculum Learning strategy for better convergence
- Applied efficient Transformer solutions for training and inference acceleration

**Research Intern @ Tencent AI Lab, Palo Alto, CA**

05/2019-08/2019

Advised by Dr. Shih-Yao Lin, Dr. Yusheng Xie and Dr. Wei Fan

**Hand Synthesis from Pose and Style: Data Augmentation for 3D Hand Pose Estimation [MM-20]**

- Defined the problem of hand synthesis from pose and style
- Proposed a cGAN-based style transfer approach to synthesize hands from conditioned pose and style
- Proposed a geometry-based curriculum training and inference with nearest-neighbor match by hand pose similarity.

**Research Intern @ Adobe Research, San Jose, CA**

01/2019-04/2019

Advised by Dr. Zhaowen Wang, Dr. Jianming Zhang and Dr. Hailin Jin

**Visual Privacy Shredder: Machine Unlearning for Privacy Protection in Generative Models [TOMM-21]**

- Investigated the memorization issue of generative models on training data
- Explored GAN intra-mode collapse and calibrated the collapse in a black-box setting: no access to training data or model parameters
- Devised a set of sampling-based tools that can visualize, quantify, and rectify intra-mode collapse.

**Research Intern @ USC Institute for Creative Technologies, Los Angeles, CA** 05/2018-08/2018

Advised by Dr. Priya Narayanan and Dr. Heesung Kwon

**Object Detection in Low-Quality Drone Imagery [ICCV-19]**

- Formulated an adversarial learning pipeline to improve the robustness of drone-based object detection
- Utilized the free attributes of flying altitude, viewing angle and weather condition to learn domain-robust features via an adversarial training framework

**Research Intern @ Siemens PLM Software, Cincinnati, OH**

05/2016-08/2016

Advised by Dr. Pengcheng Liu

*Visual Recognition using Deep Learning*

- Built a 5-layer-ConvNet to classify images generated from CAD software using TensorFlow
- Leveraged LSTM+CNN architecture to localize multiple objects of interest in one image

**Research Intern @ Siemens PLM Software, Shanghai, China**

07/2014-02/2015

Advised by Dr. George Allen (the Chief Scientist)

*1. Modeling with Curved Triangles*

- Worked on a curved triangle algorithm to give better results in graphical display
- Derived the Curved Triangle as a triangular Bezier patch from a flat triangle with 3 normals to 3 points
- Implemented the curved triangles using NXOpen libraries, and tested on different geometric models
- Application: tessellation refinement for display, 3D printing and faster model transmission

*2. Code Editor by Roslyn (Microsoft Open Compiler Technologies)*

- Improved the code editor component in NX (CAD software) using Roslyn Code Analysis technology
- Implemented an editor prototype supporting Indenting, Syntax Highlighting, Code Completion, Intellisense and Verbosity Cleaning
- Developed the editor as a Windows Forms application supporting both Visual Basic and C# features

**TEACHING EXPERIENCE****Teaching Assistant @ Texas A&M University, College Station, TX**

08/2019-05/2020

- Instructor of CSCE 421: Machine Learning
- Prepared some course materials and served in some lectures

**Teaching Assistant @ The Ohio State University, Columbus, OH**

08/2016-12/2016

- Instructor of CSE 1223: Introduction to Programming in Java
- Prepared all the course materials and served in all the lectures

**SERVICES & AWARDS****Challenge Awards**

- 1<sup>st</sup> Prize of ICCV 2021 Low-Power Computer Vision Challenge: *Video Track*
- 2<sup>nd</sup> Prize of CVPR 2020 Low-Power Computer Vision Challenge: *Video Track*

**Professional Service**

- Workshop Organizing Committee: 5th and 6th UG2+ Workshop (CVPR 2022, CVPR 2023)
- Area Chair: ICIP 2022, 2023
- Conferences Reviewers: CVPR, ECCV, ICCV, NeurIPS, ICLR, ICML, AAAI, ICME, WACV, ICIP
- Journals Reviewers: IJCV, TPAMI, TIP, TCSVT, NCAA

**Invited Talks**

- Tutorial Talk: Efficient Computer Vision for Embedded Systems (DAC 2022)
- Tutorial Talk: Designing A Low-Power Video Recognition System (CVPR 2022: ECV Workshop)
- Winner's Talk: Low-Power Computer Vision (ICCV 2021: LPCVC Workshop)
- Winner's Talk: Low-Power Computer Vision (CVPR 2020: LPCVC Workshop)
- Winner's Talk: Chalearn LAP Inpainting Competition (ECCV 2018: LAPC Workshop)

**Media Coverage**

- Research @ Texas A&M: *New technique protects privacy from snoopers who hack smart devices*
- News of Texas A&M University Engineering: *New privacy filter for smart camera applications*
- News of Adobe Research: *Smart Home? Adversarial Machine Learning Could Protect Your Privacy*